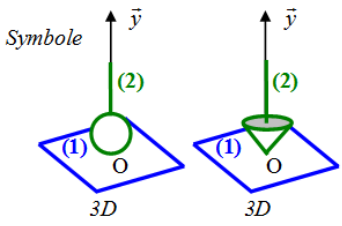
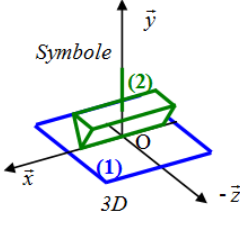
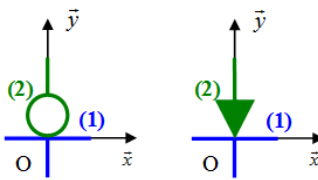
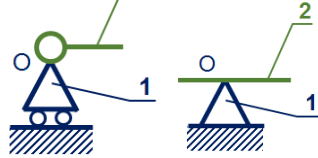
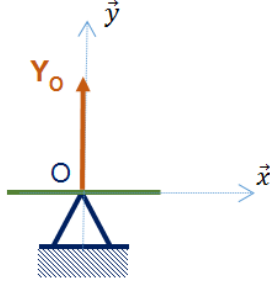
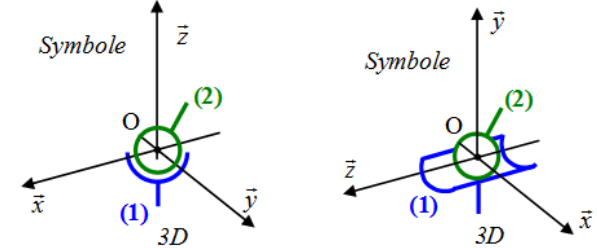
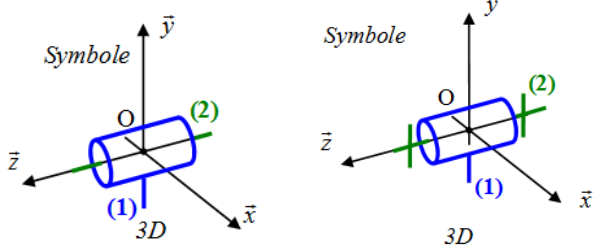
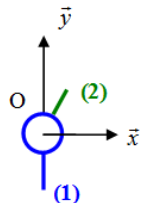
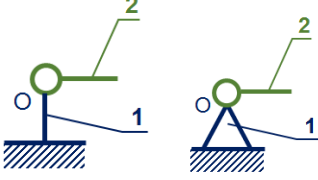
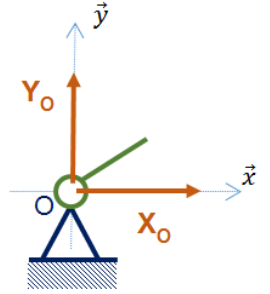
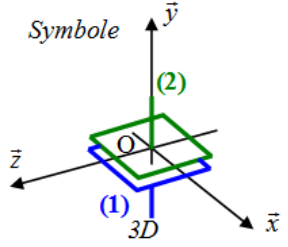
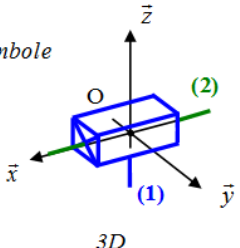
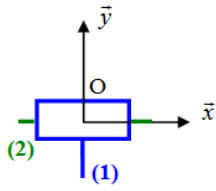
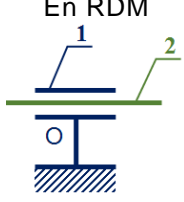


Synthèse – Liaisons dans le plan xy

Représentation 3D	Représentation 2D	Actions transmissibles et schéma
<p><i>Symbole</i></p>  <p>Ponctuelle Oy</p>  <p>LinéiqueOy</p>	<p>Ponctuelle</p>  <p>En RDM</p> 	$\begin{Bmatrix} 0 & \theta \\ Y & \theta \\ \theta & 0 \end{Bmatrix}_o \quad \begin{Bmatrix} 0 & L \\ Y & \theta \\ \theta & 0 \end{Bmatrix}_o$ 
<p><i>Symbole</i></p>  <p>Rotule O</p> <p>Linéaire annulaire Oz</p> <p><i>Symbole</i></p>  <p>Pivot glissant Oz</p> <p>Pivot Oz</p>	<p>Articulation</p>  <p>En RDM</p> 	$\begin{Bmatrix} X & \theta \\ Y & \theta \\ Z & 0 \end{Bmatrix}_o \quad \begin{Bmatrix} X & \theta \\ Y & \theta \\ \theta & 0 \end{Bmatrix}_o$ $\begin{Bmatrix} X & L \\ Y & M \\ \theta & 0 \end{Bmatrix}_o \quad \begin{Bmatrix} X & L \\ Y & M \\ Z & 0 \end{Bmatrix}_o$ 
<p><i>Symbole</i></p>  <p>Appui plan Oy</p> <p><i>Symbole</i></p>  <p>Glissière Ox</p>	<p>Glissière</p>  <p>En RDM</p> 	$\begin{Bmatrix} 0 & L \\ Y & \theta \\ \theta & N \end{Bmatrix}_o \quad \begin{Bmatrix} 0 & L \\ Y & M \\ Z & N \end{Bmatrix}_o$ 